

Code.No: 07A50503

R07

SET-1

III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010
COMPUTER GRAPHICS
(COMMON TO CSE, IT, CSSE, E.COMP.E)

Time: 3hours**Max.Marks:80**

Answer any FIVE questions
All questions carry equal marks

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- 1.a) Discuss the operation of raster scan system with a neat sketch.
b) Write about any one input device. [8+8]
- 2.a) Derive the necessary equations to generate bresenham line algorithm.
b) Write the bresenham line algorithm. [8+8]
- 3.a) Give the transformation matrix to rotate a point about an arbitrary point.
b) Show that the transformation matrix for a reflection about the line $y=-x$ is equivalent to a reflection relative to the y -axis followed by a counterclockwise rotation of 90° . [8+8]
4. With an example explain Cohen Sutherland line clipping algorithm. [16]
- 5.a) Enumerate the properties of B spline curves.
b) Explain Gouraud shading. [8+8]
- 6.a) Derive the transformation matrix for parallel projections.
b) Give the transformation matrix for rotation about X-axis in 3D. [8+8]
- 7.a) Write about area subdivision algorithm for back face detection.
b) Enumerate the disadvantages of depth buffer algorithm. [8+8]
- 8.a) Write about different motion specifications.
b) Write about different computer animation languages. [8+8]

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SET-2

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COMPUTER GRAPHICS
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Time: 3hours**Max.Marks:80**

Answer any FIVE questions
All questions carry equal marks

- - -

- 1.a) Differentiate raster and random scan display systems.
b) Discuss about any one display device. [8+8]
2. Derive the necessary equations required to generate circle algorithm. [16]
- 3.a) Derive the transformation matrix to rotate a point about origin.
b) Give the transformation matrix to reflect a point about an arbitrary axis. [8+8]
4. Explain cyrus-beck line clipping algorithm. [16]
- 5.a) Enumerate the properties of Beizer curves.
b) List the properties to be considered for calculating the intensity to be rendered at a point on an object. Give the basic illumination model. [8+8]
- 6.a) Give transformation matrix to rotate a point about X-axis.
b) With a block diagram, explain 3D viewing. [8+8]
- 7.a) Explain depth-buffer algorithm for hidden surface removal.
b) Write about octree method for back face detection. [8+8]
- 8.a) What are the steps in the design of animation sequence.
b) List various motion specifications. [8+8]

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SET-3

III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010
COMPUTER GRAPHICS
(COMMON TO CSE, IT, CSSE, E.COMPE)

Time: 3hours**Max.Marks:80**

Answer any FIVE questions
All questions carry equal marks

- - -

- 1.a) Write about flat-panel displays.
b) Write about Digitizers. [8+8]
- 2.a) Explain scan line polygon filling algorithm.
b) Differentiate scan line and seed fill algorithms for polygon filling. [8+8]
- 3.a) Derive transformation matrix to rotate a point about origin.
b) Show that the transformation matrix for a reflection about the line $y=x$ is equivalent to a reflection relative to the x-axis followed by a counterclockwise rotation of 90° . [8+8]
4. Explain sudherland – hodgman algorithm for polygon clipping with an example. [16]
- 5.a) List the properties of B-splines.
b) Write about phong shading model. [8+8]
- 6.a) Give the transformation matrix in 3D for the following:
i) To rotate a point about the y-axis by 45° in counter clock wise direction. [8+8]
ii) Reflect a point about x-axis.
b) With a block diagram, write about 3D viewing. [8+8]
7. Write about the following hidden surface methods
a) Depth sorting
b) BSP-bee. [8+8]
- 8.a) What are the steps involved in the design of animation sequence.
b) Write about different computer animation languages. [8+8]

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SET-4

III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010
COMPUTER GRAPHICS
(COMMON TO CSE, IT, CSSE, E.COMP.E)

Time: 3hours**Max.Marks:80**

Answer any FIVE questions
All questions carry equal marks

- - -

- 1.a) Discuss the operation of random scan system with a neat sketch.
b) Write about any one display device. [8+8]
- 2.a) Differentiate scan-line and seed fill algorithms for polygon filling.
b) Explain scan-line polygon filling algorithm. [8+8]
- 3.a) Derive the transformation matrix to rotate, a point about arbitrary point.
b) Give the transformation matrix for the following
i) To shift left by 2 units and then to rotate by 45° clockwise.
ii) To reflect w.r.t. $y=-x$ axis. [8+8]
4. Explain Cohen – Sutherland algorithm for line clipping with an example. [16]
- 5.a) Explain hermite method of curve generations.
b) Discuss the necessary factors contributing to intensity calculations. Give Basic illumination model. [8+8]
- 6.a) Derive the transformation matrix for perspective transformation.
b) Give transformation matrix to rotate a point about Y-axis in counterclockwise direction. [8+8]
7. Explain the following hidden surface removal algorithms.
i) Depth – Sorting.
ii) Octree. [16]
- 8.a) What are key frames? Write about morphing.
b) Explain some of motion specification for computer animation. [8+8]

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